

Monads and More: Part 4

Tarmo Uustalu, Institute of Cybernetics, Tallinn

University of Nottingham, 14–18 May 2007

University of Udine, 2–6 July 2007

Comonads

- Comonads are the dual of monads.
- A *comonad* is a
 - a functor $D : \mathcal{C} \rightarrow \mathcal{C}$ (the *underlying functor*),
 - a natural transformation $\eta : D \rightarrow \text{Id}_{\mathcal{C}}$ (the *counit*),
 - a natural transformation $\delta : D \rightarrow DD$ (the *comultiplication*)

satisfying these conditions:

$$\begin{array}{ccc} DA & \xrightarrow{\delta_A} & DDA \\ \delta_A \downarrow & \searrow & \downarrow D\epsilon_A \\ DDA & \xrightarrow{\epsilon_{DA}} & DA \end{array} \qquad \begin{array}{ccc} DA & \xrightarrow{\delta_A} & DDA \\ \delta_A \downarrow & & \downarrow D\delta_A \\ DDA & \xrightarrow{\delta_{DA}} & DDDA \end{array}$$

- In other words, a comonad is comonoid in $[\mathcal{C}, \mathcal{C}]$ (a monoid in $[\mathcal{C}, \mathcal{C}]^{\text{op}}$).

CoKleisli triples

- A *coKleisli triple* is given by
 - an object mapping $D : |\mathcal{C}| \rightarrow |\mathcal{C}|$,
 - for any object A , a map $\varepsilon_A : DA \rightarrow A$,
 - for any map $k : DA \rightarrow B$, a map $k^\dagger : DA \rightarrow DB$ (the *coKleisli extension* operation)

satisfying

- if $k : DA \rightarrow B$, then $\varepsilon_B \circ k^\dagger = k$,
 - $\varepsilon_A^\dagger = \text{id}_{DA}$,
 - if $k : DA \rightarrow B$, $\ell : DB \rightarrow C$, then $(\ell \circ k^\dagger)^\dagger = \ell^\dagger \circ k^\dagger$.
- There is a bijection between comonads and coKleisli triples.

CoKleisli category of a comonad

- A comonad D on a category \mathcal{C} induces a category **CoKI**(D) called the *coKleisli category* of D defined by
 - an object is an object of \mathcal{C} ,
 - a map of from A to B is a map of \mathcal{C} from DA to B ,
 - $\text{id}_A^D =_{\text{df}} DA \xrightarrow{\varepsilon_A} A$,
 - if $k : A \rightarrow^D B$, $\ell : B \rightarrow^D C$, then
$$\ell \circ^D k =_{\text{df}} DA \xrightarrow{\mu_A} DDA \xrightarrow{Dk} DB \xrightarrow{\ell} C.$$
- From \mathcal{C} there is an identity-on-objects *inclusion functor* J to **CoKI**(D), defined on maps by
 - if $f : A \rightarrow B$, then
$$Jf =_{\text{df}} DA \xrightarrow{\varepsilon_A} A \xrightarrow{f} B = DA \xrightarrow{Df} DB \xrightarrow{\varepsilon_B} B.$$
- The functor J has a left adjoint $U : \mathbf{CoKI}(D) \rightarrow \mathcal{C}$ given by $UA =_{\text{df}} DA$, if $k : A \rightarrow^D B$, then $Uk =_{\text{df}} DA \xrightarrow{k^\dagger} DB$.

Comonadic notions of computation

- We think of \mathcal{C} as the category of pure functions and of DA as the type of coeffectful computations of values of type A (values in context).
- **CoKI**(D) is the category of coeffectful or context-dependent functions.
- $\varepsilon_A : DA \rightarrow A$ is the identity on A seen as trivially context-dependent (discarding the context).
- $Jf : DA \rightarrow B$ is a general pure function $f : A \rightarrow B$ regarded as trivially context-dependent.
- $\delta_A : DA \rightarrow DDA$ blows the context of a value up (duplicates the context).
- $k^\dagger : DA \rightarrow DB$ is a context-dependent function $k : DA \rightarrow B$ extended into one that can output a value of in a context (e.g., for a postcomposed context-dependent function).

Examples

- Product comonad, for dependency on an environment:
 - $DA =_{\text{df}} A \times E$ where E is an object of \mathcal{C} ,
 - $\varepsilon_A =_{\text{df}} A \times E \xrightarrow{\text{fst}} A$,
 - $\delta_A =_{\text{df}} A \times E \xrightarrow{\langle \text{id}, \text{snd} \rangle} (A \times E) \times E$,
 - if $k : A \times E \rightarrow B$, then $k^\dagger =_{\text{df}} A \times E \xrightarrow{\langle k, \text{snd} \rangle} B \times E$.
- This is the dual of the exceptions monad.
- It is not very interesting, as $\mathbf{CoKI}(D) \cong \mathbf{KI}(T)$ for $TA =_{\text{df}} E \Rightarrow A$ (the reader monad).

- Exponent comonad:

- $DA =_{\text{df}} E \Rightarrow A$ where (E, e, m) is a monoid in \mathcal{C} ,

- $\varepsilon_A =_{\text{df}} (E \Rightarrow A) \xrightarrow{\text{ur}^{-1}} (E \Rightarrow A) \times 1$

- $\delta_A =_{\text{df}} \Lambda(\Lambda(((E \Rightarrow A) \times E) \xrightarrow{\text{id} \times e} (E \Rightarrow A) \times E \xrightarrow{\text{ev}} A, (E \Rightarrow A) \times E \xrightarrow{a} (E \Rightarrow A) \times (E \times E) \xrightarrow{\text{id} \times m} (E \Rightarrow A) \times E \xrightarrow{\text{ev}} A)),$

- Interesting special cases are $(E, e, m) =_{\text{df}} (\text{Nat}, 0, +)$ and $(E, e, m) =_{\text{df}} (\text{Nat}, 0, \max)$.

- “Comonad” comonad:
 - $DA =_{\text{df}} (S \Rightarrow A) \times S$ where S is an object of \mathcal{C} ,
 - $\varepsilon_A =_{\text{df}} (S \Rightarrow A) \times S \xrightarrow{\text{ev}} A$,
 - if $k : (S \Rightarrow A) \times S \rightarrow B$, then

$$k^\dagger =_{\text{df}} (S \Rightarrow A) \times S \xrightarrow{\wedge(k) \times \text{id}} (S \Rightarrow B) \times S.$$
- This comonad arises from the adjunction $S \times - \dashv S \Rightarrow -$.

Symmetric monoidal functors

- A *strong/lax symmetric monoidal functor* between symmetric monoidal categories $(\mathcal{C}, I, \otimes)$ and $(\mathcal{D}, I', \otimes')$ is
 - a functor on $F : \mathcal{C} \rightarrow \mathcal{D}$
 - together with an isomorphism/map $e : I' \rightarrow FI$
 - and a natural isomorphism/transformation with components $m_{A,B} : FA \otimes' FB \rightarrow F(A \otimes B)$

satisfying

$$\begin{array}{ccc}
 FA \otimes' I' & \xrightarrow{\text{id} \otimes' e'} & FA \otimes' FI & \xrightarrow{m_{A,I}} & F(A \otimes I) & & FA \otimes' FB & \xrightarrow{m_{A,B}} & F(A \otimes B) \\
 \text{ur}'_{FA} \downarrow & & & & \downarrow F_{ur_A} & & c'_{FA,FB} \downarrow & & \downarrow F_{c_{A,B}} \\
 FA & \xlongequal{\quad\quad\quad} & FA & & & & FB \otimes' FA & \xrightarrow{m_{B,A}} & F(B \otimes A)
 \end{array}$$

$$\begin{array}{ccc}
 (FA \otimes' FB) \otimes' FC & \xrightarrow{m_{A,B} \otimes \text{id}} & F(A \otimes B) \otimes' FC & \xrightarrow{m_{A \otimes B, C}} & F((A \otimes B) \otimes C) \\
 a'_{FA,FB,FC} \downarrow & & & & \downarrow F_{a_{A,B,C}} \\
 FA \otimes' (FB \otimes' FC) & \xrightarrow{\text{id} \otimes m_{B,C}} & FA \otimes' F(B \otimes C) & \xrightarrow{m_{A, B \otimes C}} & F(A \otimes (B \otimes C))
 \end{array}$$

- A *symmetric monoidal natural transformation* between two (strong or lax) symmetric monoidal functors (F, e, m) , (G, e', m') is a natural transformation $\tau : F \rightarrow G$ satisfying

$$\begin{array}{ccc}
 I' & \xrightarrow{e} & FI \\
 \parallel & & \downarrow \tau_I \\
 I' & \xrightarrow{e'} & GI
 \end{array}
 \qquad
 \begin{array}{ccc}
 FA \otimes' FB & \xrightarrow{m_{A,B}} & F(A \otimes B) \\
 \tau_A \otimes' \tau_B \downarrow & & \downarrow \tau_{A \otimes B} \\
 GA \otimes' GB & \xrightarrow{m'_{A,B}} & G(A \otimes B)
 \end{array}$$

Symmetric monoidal comonads

- A *strong/lax symmetric monoidal comonad* on a symmetric monoidal category $(\mathcal{C}, I, \otimes)$ is a comonad (D, ε, δ) where D is a strong/lax symmetric monoidal functor (with I, \otimes preserved by e, m) and ε, δ are symmetric monoidal natural transformations, i.e., satisfy

$$\begin{array}{ccc}
 I \xrightarrow{e} DI & & I \xrightarrow{e} DI \\
 \parallel & & \parallel \\
 I \xrightarrow{=} I & & I \xrightarrow{e} DI \xrightarrow{D_e} DDI \\
 & & \downarrow \delta_I \\
 & & DDI
 \end{array}$$

$$\begin{array}{ccc}
 DA \otimes DB \xrightarrow{m_{A,B}} D(A \otimes B) & & \\
 \varepsilon_A \otimes \varepsilon_B \downarrow & & \downarrow \varepsilon_{A \otimes B} \\
 A \otimes B \xrightarrow{=} A \otimes B & &
 \end{array}$$

$$\begin{array}{ccc}
 DA \otimes DB & \xrightarrow{m_{A,B}} & D(A \otimes B) \\
 \delta_A \otimes \delta_B \downarrow & & \downarrow \delta_{A \otimes B} \\
 DDA \otimes DDB & \xrightarrow{m_{DA,DB}} D(DA \otimes DB) \xrightarrow{Dm_{A,B}} & DD(A \otimes B)
 \end{array}$$

- (Note that Id is always symmetric monoidal and F, G being symmetric monoidal imply that GF is symmetric monoidal too.)
- A strong/lax symmetric *semimonoidal* comonad is as a strong/lax symmetric monoidal comonad, but without e (on a category which may be without I).

Dataflow computations

Dataflow computation = discrete-time signal transformations
= stream functions.

The output value at a time instant (stream position) is determined by the input value at the same instant (position) plus further input values.

Example dataflow programs

$$\begin{aligned} pos &= 0 \text{ fby } (pos + 1) \\ sum\ x &= x + (0 \text{ fby } (sum\ x)) \\ fact &= 1 \text{ fby } (fact * (pos + 1)) \\ fibo &= 0 \text{ fby } (fibo + (1 \text{ fby } fibo)) \end{aligned}$$

<i>pos</i>	0	1	2	3	4	5	6	...
<i>sum pos</i>	0	1	3	6	10	15	21	...
<i>fact</i>	1	1	2	6	24	120	720	...
<i>fibo</i>	0	1	1	2	3	5	8	...

We want to consider functions $\text{Str } A \rightarrow \text{Str } B$ as impure functions from A to B .

Streams are naturally isomorphic to functions from natural numbers: $\text{Str } A =_{\text{df}} \nu X. A \times X \cong \text{Nat} \Rightarrow A$.

General stream functions $\text{Str } A \rightarrow \text{Str } B$ are thus in natural bijection with maps $\text{Str } A \times \text{Nat} \rightarrow B$.

Comonad for general stream functions

- Functor:

$$DA =_{\text{df}} (\text{Nat} \Rightarrow A) \times \text{Nat} \cong \text{List}A \times \text{Str}A$$

- Input streams with past/present/future:

$$a_0, a_1, \dots, a_{n-1}, \boxed{a_n}, a_{n+1}, a_{n+2}, \dots$$

- Counit:

$$\begin{array}{lcl} \varepsilon_A : (\text{Nat} \Rightarrow A) \times \text{Nat} & \rightarrow & A \\ & (a, n) & \mapsto a(n) \end{array}$$

- CoKleisli extension:

$$\frac{k : (\text{Nat} \Rightarrow A) \times \text{Nat} \rightarrow B}{k^* : (\text{Nat} \Rightarrow A) \times \text{Nat} \rightarrow (\text{Nat} \Rightarrow B) \times \text{Nat}}$$
$$(a, n) \mapsto (\lambda m k(a, m), n)$$

Comonad for causal stream functions

- Functor: $DA =_{\text{df}} \text{NEList} \cong \text{List}A \times A$
- Input streams with past and present but no future
- Counit:

$$\begin{aligned} \varepsilon_A : \text{NEList}A &\rightarrow A \\ [a_0, \dots, a_n] &\mapsto a_n \end{aligned}$$

- CoKleisli extension:

$$\frac{k : \text{NEList}A \rightarrow B}{k^* : \text{NEList}A \rightarrow \text{NEList}B}$$
$$[a_0, \dots, a_n] \mapsto [k[a_0], k[a_0, a_1], \dots, k[a_0, \dots, a_n]]$$

Comonad for anticausal stream functions

- Input streams with present and future but no past
- Functor: $DA =_{\text{df}} \text{Str}A \cong A \times \text{Str}A$

Relabelling tree transformations

- Let $H : \mathcal{C} \rightarrow \mathcal{C}$. Define $\text{Tree}A =_{\text{df}} \mu X. A \times HX$. We are interested in relabelling functions $\text{Tree}A \rightarrow \text{Tree}B$.
(Alt. we can define $\text{Tree}^\infty A =_{\text{df}} \nu X. A \times HX$ and interest ourselves in relabelling functions $\text{Tree}^\infty A \rightarrow \text{Tree}^\infty B$.)
- Comonad for general relabelling functions:

$$DA =_{\text{df}} \text{Tree}'A \times A \cong \text{Path}A \times \text{Tree}A$$

where $\text{Path}A =_{\text{df}} \mu X. 1 + A \times H'(A \times X)$ (Huet's zipper).

- E.g., for $HX =_{\text{df}} 1 + X \times X$, $H'X \cong 2 \times X$ and $\text{Path}A \cong \mu X. 1 + A \times 2 \times \text{Tree}A \times X$.
- Comonad for bottom-up relabelling functions:

$$DA =_{\text{df}} \text{Tree}A$$

Cartesian preclosed structure of the coKleisli category of a strong/lax (semi)monoidal comonad

- Let D be a comonad on a Cartesian closed category \mathcal{C} .
- Since $J : \mathcal{C} \rightarrow \mathbf{CoKI}(D)$ is a right adjoint and preserves limits, $\mathbf{CoKI}(D)$ inherits products from \mathcal{C} . Explicitly, we can define

$$\begin{aligned} A \times^D B &=_{\text{df}} A \times B \\ \pi_0^D &=_{\text{df}} \text{fst} \circ \varepsilon \\ \pi_1^D &=_{\text{df}} \text{snd} \circ \varepsilon \\ \langle k_0, k_1 \rangle^D &=_{\text{df}} \langle k_0, k_1 \rangle \end{aligned}$$

- If D is $(1, \times)$ strong/lax symmetric semimonoidal, then we can also define

$$\begin{aligned}
 A \Rightarrow^D B &=_{\text{df}} DA \Rightarrow B \\
 \text{ev}^D &=_{\text{df}} \text{ev} \circ \langle \varepsilon \circ D\text{fst}, D\text{snd} \rangle \\
 \Lambda^D(k) &=_{\text{df}} \Lambda(k \circ m)
 \end{aligned}$$

$$D((DA \Rightarrow B) \times A) \xrightarrow{\langle \varepsilon \circ D\text{fst}, D\text{snd} \rangle} (DA \Rightarrow B) \times DA \xrightarrow{\text{ev}} B$$

$$\frac{DC \times DA \xrightarrow{m} D(C \times A) \xrightarrow{k} B}{DC \xrightarrow{\Lambda(k \circ m)} DA \Rightarrow B}$$

- Using a strength (if available) is not a good idea: We have no multiplication

$$DC \times DA \xrightarrow{\text{sl}} D(C \times DA) \xrightarrow{D\text{sr}} DD(C \times A) \xrightarrow{?} D(C \times A)$$

and applying ε or $D\varepsilon$ gives a solution where the order of arguments of a function is important and coefficients do not combine:

$$DC \times DA \xrightarrow{\text{id} \times \varepsilon} DC \times A \xrightarrow{\text{sl}} D(C \times A)$$

or

$$DC \times DA \xrightarrow{\varepsilon \times \text{id}} C \times DA \xrightarrow{\text{sr}} D(C \times A)$$

- If D is strong semimonoidal (in which case it is automatically strong symmetric semimonoidal as well), then $A \Rightarrow^D -$ is right adjoint to $- \times^D A$ and hence \Rightarrow^D is an exponent functor:

$$\frac{\frac{D(C \times A) \rightarrow B}{DC \times DA \rightarrow B}}{DC \rightarrow DA \Rightarrow B}$$

- This is the case, e.g., if $DA \cong \nu X.A \times (E \Rightarrow X)$ for some E (e.g., $DA \cong \text{Str}A \cong \nu X.A \times (1 \Rightarrow X)$).

- More typically, D is only lax symmetric semimonoidal.
- Then it suffices to have m satisfying

$$\begin{array}{ccc}
 DA & \xlongequal{\quad} & DA \\
 \Delta_{DA} \downarrow & & \downarrow D\Delta_A \\
 DA \times DA & \xrightarrow{m_{A,A}} & D(A, A)
 \end{array}$$

where $\Delta = \langle \text{id}, \text{id} \rangle : A \rightarrow A \times A$ is part of the comonoid structure on the objects of \mathcal{C} , to get that $m \circ \langle D\text{fst}, D\text{snd} \rangle = \text{id}$ and that \Rightarrow^D is a weak exponent operation on objects. It is not functorial (not even in each argument separately).

Partial uniform parameterized fixpoint operator

Let $F : \mathcal{C} \rightarrow \mathcal{C}$. Define $DA =_{\text{df}} \nu Z.A \times FZ$.

Call a coKleisli map $k : A \times B \rightarrow^D B$ *guarded* if for some k' we have

$$\begin{array}{ccc} D(A \times B) & \xrightarrow{k} & B \\ \downarrow \cong & & \uparrow k' \\ (A \times B) \times FD(A \times B) & \xrightarrow{\text{fst} \times \text{id}} & A \times FD(A \times B) \end{array}$$

For any guarded $k : A \times B \rightarrow^D B$, there is a unique map $\text{fix}(k) : A \rightarrow^D B$ satisfying

$$\begin{array}{ccc} A & \xrightarrow{\text{fix}(k)} & B \\ & \searrow & \nearrow k \\ & (A \times B) & \end{array}$$

$\langle \text{id}^D, \text{fix}(k) \rangle^D$

fix is a partial *Conway operator* defined on guarded maps, i.e., besides the *fixpoint property*, for any guarded $k : A \times^D B \rightarrow^D B$,

$$\text{fix}(k) = k \circ^D \langle \text{id}^D, \text{fix}(k) \rangle^D$$

it satisfies *naturality* in A , *dinaturality* in B , and the *diagonal property*: for any guarded $k : A \times^D B \times^D B \rightarrow^D B$,

$$\text{fix}(k \circ^D (\text{id}^D \times^D \Delta^D)) = \text{fix}(\text{fix}(k))$$

Wrt. pure maps, fix is also *uniform* (i.e., strongly dinatural in B instead of dinatural), i.e., for any guarded $k : A \times^D B \rightarrow^D B$, $\ell : A \times^D B' \rightarrow^D B'$ and $h : B \rightarrow B'$

$$Jh \circ^D k = \ell \circ^D (\text{id}^D \times^D Jh) \implies Jh \circ^D \text{fix}(k) = \text{fix}(\ell)$$

Comonadic semantics

- As in the case of monadic semantics, we interpret the lambda-calculus into $\mathbf{CoKI}(D)$ in the standard way (using its Cartesian preclosed structure), getting

$$\begin{aligned} \llbracket K \rrbracket^D &=_{\text{df}} \text{ an object of } \mathbf{CoKI}(D) \\ &= \text{ that object of } \mathcal{C} \\ \llbracket A \times B \rrbracket^D &=_{\text{df}} \llbracket A \rrbracket^D \times^D \llbracket B \rrbracket^D \\ &= \llbracket A \rrbracket^D \times \llbracket B \rrbracket^D \\ \llbracket A \Rightarrow B \rrbracket^D &=_{\text{df}} \llbracket A \rrbracket^D \Rightarrow^D \llbracket B \rrbracket^D \\ &= D\llbracket A \rrbracket^D \Rightarrow \llbracket B \rrbracket^D \\ \llbracket \underline{C} \rrbracket^D &=_{\text{df}} \llbracket C_0 \rrbracket^D \times \dots \times \llbracket C_{n-1} \rrbracket^D \\ &= \llbracket C_0 \rrbracket \times \dots \times \llbracket C_{n-1} \rrbracket \end{aligned}$$

$$\begin{aligned}
\llbracket (\underline{x}) x_i \rrbracket^D &=_{\text{df}} \pi_i^D \\
&= \pi_i \circ \varepsilon \\
\llbracket (\underline{x}) \text{fst}(t) \rrbracket^D &=_{\text{df}} \pi_0^D \circ^D \llbracket (\underline{x}) t \rrbracket^D \\
&= \text{fst} \circ \llbracket (\underline{x}) t \rrbracket^D \\
\llbracket (\underline{x}) \text{snd}(t) \rrbracket^D &=_{\text{df}} \pi_1^D \circ^D \llbracket (\underline{x}) t \rrbracket^D \\
&= \text{snd} \circ \llbracket (\underline{x}) t \rrbracket^D \\
\llbracket (\underline{x}) (t_0, t_1) \rrbracket^D &=_{\text{df}} \langle \llbracket (\underline{x}) t_0 \rrbracket^D, \llbracket (\underline{x}) t_1 \rrbracket^D \rangle^D \\
&= \langle \llbracket (\underline{x}) t_0 \rrbracket^D, \llbracket (\underline{x}) t_1 \rrbracket^D \rangle \\
\llbracket (\underline{x}) \lambda x t \rrbracket^D &=_{\text{df}} \Lambda^D(\llbracket (\underline{x}, x) t \rrbracket^D) \\
&= \Lambda(\llbracket (\underline{x}, x) t \rrbracket^D \circ m) \\
\llbracket (\underline{x}) t u \rrbracket^D &=_{\text{df}} \text{ev}^D \circ^D \langle \llbracket (\underline{x}) t \rrbracket^D, \llbracket (\underline{x}) u \rrbracket^D \rangle^D \\
&= \text{ev} \circ \langle \llbracket (\underline{x}) t \rrbracket^D, (\llbracket (\underline{x}) u \rrbracket^D)^\dagger \rangle
\end{aligned}$$

- Coeffect-specific constructs are interpreted specifically.
- E.g., for the constructs of a general/causal/anticausal dataflow language we can use the appropriate comonad and define:

$$\begin{aligned} \llbracket (\underline{x}) t \text{ fby } u \rrbracket^D &=_{\text{df}} \text{fby} \circ \langle \llbracket (\underline{x}) t \rrbracket^D, (\llbracket (\underline{x}) u \rrbracket^D)^\dagger \rangle^D \\ \llbracket (\underline{x}) t \text{ next } u \rrbracket^D &=_{\text{df}} \text{next} \circ (\llbracket (\underline{x}) t \rrbracket^D)^\dagger \end{aligned}$$

- Again, we have soundness of typing, in the form $\underline{x} : \underline{C} \vdash t : A$ implies $\llbracket (\underline{x})t \rrbracket^D : \llbracket \underline{C} \rrbracket^D \rightarrow^D \llbracket A \rrbracket^D$, but not all equations of the lambda-calculus are validated.
- For a closed term $\vdash t : A$, soundness of typing says that $\llbracket t \rrbracket^D : 1 \rightarrow^D \llbracket A \rrbracket^D$, i.e., $D1 \rightarrow \llbracket A \rrbracket^D$, so closed terms are evaluated relative to a coefficient over 1.
- In case of general or causal stream functions, an element of $D1$ is a list over 1, i.e., a natural number, the time elapsed.
- If D is strong or lax symmetric monoidal (not just semimonoidal), we have a canonical choice $e : 1 \rightarrow D1$.

- Comonadic dataflow language semantics: The first-order language agrees perfectly with Lucid and Lustre by its semantics.

The meaning of higher-order dataflow computation has been unclear. We get a neat semantics from mathematical considerations (cf. Colaço, Pouzet's design with two flavors of function spaces).

Symmetric monoidal comonads (and strong monads) in linear / modal logic

- Strong symmetric monoidal comonads are central in the semantics of intuitionistic linear logic and modal logic to interpret the $!$ and \Box (\diamond) operators.
- Linear logic: Benton, Bierman, de Paiva, Hyland; Bierman; Benton; Mellies; Maneggia; etc.
- Modal logic: Bierman, de Paiva.
- Applications to staged computation and semantics of names: Pfenning, Davies, Nanevski.